

1 Milking parlor evaluation – How to get started with assessments

2 Patrick J. Gorden, DVM, PhD, DABVP, DACVCP

3 Veterinary Diagnostic and Production Animal Medicine

4 Iowa State University College of Veterinary Medicine

5 Ames, IA 50011

6 Abstract

7 Dairy farmers have been utilizing machine milking to collect milk from cows for almost 200
8 years. Despite the long and storied history of machine milking, the milking machine plays an
9 important role in the maintenance of quality milk production. As veterinarians, we are skilled in
10 physiology and bacteriology but have little understanding of milk machine function.
11 Veterinarians can expand their service offerings to improve milk quality by systematically
12 evaluating machine function and understanding the impacts of recommended changes. Machine
13 milking aims to help maintain good milk quality by creating an environment that removes milk
14 in a clean, gentle, and complete manner. This environment is created by coupling machine
15 settings with milking liners and the activities of milk harvest technicians to minimize
16 overmilking of cows, as overmilking leads to unwanted changes in teats. However, evaluating
17 milking equipment without assessing milk harvest technician activity, the cows and their
18 environment, and overall farm management will often fail to lead to improvements in milk
19 quality.

20 Keywords: milk equipment evaluation, claw vacuum, milk quality

21 Introduction

22 It has been known for centuries that milk from cows and other ruminants provides a significant
23 nutritional resource. As population growth occurred throughout the world during the early 1800s,
24 there were continuous attempts to make milk collection more efficient. Early attempts included
25 locating farms near population centers. Labor was cheap and plentiful during these times, so
26 mechanization was not considered practical. It was only when the countries of Australia and
27 New Zealand became territories that the mechanization of the milking process began. In the early
28 1800s, simple cannulas placed into teats to drain milk into attached buckets were the first devices
29 to mechanize milking. The power for such devices was provided by gravity and intra-mammary
30 pressure. The first patent was applied for in 1836 by Burton. This technology was fraught with
31 problems, especially the transfer of mastitis pathogens from cow to cow.³

32 Commercial manufacturing of double action milking units began in 1917 by Delaval, who
33 introduced the Delaval Bucket Milking Machine, and Babson Bros., who manufactured the first
34 Surge milker later that year. These units remained in production for over a quarter of a century

35 and were used by about one-half of the dairy farmers in the United States who had machine
36 milkers. Through the 1950's there was continued slow improvement of milking systems.
37 Although most of the milking was still done utilizing bucket milkers, single and double parlors
38 that milked cows directly into pipelines began to emerge. In 1930, the first rotary milking parlor
39 appeared in the United States. Also, in 1930, Delaval introduced electronics with the release of
40 the electromagnetic pulsator. This pulsator was utilized through the 1950s with great success
41 until more sophisticated models replaced it. Since then, electronics have been incorporated into
42 every milking and milking management aspect. Methods for evaluating milking system
43 performance began to appear in the 1950s, along with improved methods for cleaning milking
44 systems.³

45 This article aims to lay the foundation for understanding modern milking systems and how
46 individuals should systematically assess these milking systems. There is a lot of individualization
47 in evaluation processes and opinions on equipment function. Machine milking aims to help
48 maintain good milk quality by creating an environment that removes milk in a clean, gentle, and
49 complete manner. Therefore, it must be emphasized that when making recommendations, one
50 should prioritize their findings from improvements that will improve milk quality on the farm to
51 cosmetic enhancements.

52 Guidelines for System Design and Evaluation of Milking Systems

53 The American Society of Agricultural and Biological Engineers (ASABE) and the International
54 Standards Organization (ISO) publish standards for the design and testing of milking systems.
55 The following documents from ASABE relating to milking system design and testing are
56 available on the ASABE website at www.asabe.org:

57 ASAE S300.4 – Milking Machine Installations – Vocabulary, Re-affirmed February
58 2008.

59 ASAE EP445.1 – Test Equipment and Its Application for Measuring Milking Machine
60 Operating Characteristics, Re-affirmed February 2008.

61 ASAE S518.2 – Milking Machine Installations – Construction and Performance, Re-
62 affirmed February 2008.

63 ISO documents can be ordered from the ISO website at www.iso.org. The following records
64 relating to milking system design and testing are available:

65 ISO 5707:2007 – Milking Machine Installations – Construction and Performance.

66 ISO 6690:2007 – Milking Machine Installations – Mechanical Tests.

67 The National Mastitis Council (NMC) publishes Procedures for Evaluating Vacuum Levels and
68 Air Flow in Milking Systems, which are guidelines for evaluating milking systems that

69 incorporate the requirements from the engineering documents into a stepwise equipment
70 evaluation procedure. This document is available from the organization's website
71 (www.nmconline.org). It should be noted that NMC is not a standards-setting organization, so
72 these documents must be utilized only as guidelines for evaluating milking system performance.
73 When developing the post-evaluation report, one must be careful not to assert that the standards
74 come from NMC but instead from the proper standards-setting organization.

75 Components of the Modern Milking Machine

76 To properly evaluate a milking system, the evaluator needs to know the essential components of
77 a milking system and understand how a milking machine functions. There are many types of
78 milking systems, from portable units that milk a few cows to very large parlors that milk 24
79 hours per day. No matter the size, all systems have the same essential components (Figure 1).

- 80 • A vacuum pump is a specialized air compressor that pulls the air source from the vacuum
81 lines of the milking system and continuously expels it into the atmosphere.
- 82 • A means to control the vacuum level.
- 83 • A system of airlines and milk lines is closed except for the milking units and the regulator
84 (if present) that moves air (vacuum) and milk away from the cow. There must be a means
85 to separate the milk from the air inside the vacuum system and allow the milk to be
86 exposed to a positive pressure system to move the milk to the storage tank. The receiver
87 group usually accomplishes this, but in a bucket system, the floor pail acts as a storage
88 vessel to separate the milk from the air.
- 89 • At least one milking unit to remove milk from the udder.
- 90 • A pulsation system to move the liner within the teacups.
- 91 • A system for cleaning and sanitizing the milking equipment between subsequent
92 milkings.
- 93 • Some systems may have additional equipment, such as automatic detachers, meter
94 systems for measuring milk production and parlor throughput, and pulsation monitoring
95 systems.

96 Vacuum Pumps

97 Vacuum pumps compress air approximately 2 to 1 to provide the necessary energy (vacuum) to
98 move air, clean chemicals, and milk (in systems that require the lifting of milk). Vacuum pumps
99 range from 5 to 400 cubic feet/min (cfm) with horsepower requirements of 1 to 40 hp depending
100 on the installation size. The sizing of the vacuum pump and the motor depends on the size of the
101 milking system and the additional components that may be added (milk sweeps, air-lubricated
102 regulators, etc.). In general, milk pumps and motors should be chosen to produce 35 cfm (1000
103 L/min) of adequate reserve plus 3 cfm (85 L/min) per milking unit for component (pulsators,
104 milking unit, etc) air usage and to account for air leakage in the system and through the
105 regulator. Therefore, a double twelve milking parlor should have a vacuum pump that will

106 produce 107 cfm (35 cfm + (24 units * 3 cfm/unit)) or 3040 L/min (1000 L/min + (85 L/min *
107 24)).

108 As a rule of thumb, the vacuum output of a pump at 15" vacuum can be determined by
109 multiplying the motor's horsepower by 7.5 – 10, depending on the pump type.

110 Vacuum Regulation

111 Milking systems are designed to maintain a stable vacuum within the milking claw. Of course,
112 the air needs of the system will fluctuate depending on various activities, i.e., unit attachment,
113 unit falloffs, milking, etc. Therefore, a system of vacuum regulation must be in place to maintain
114 stable vacuum. There are two methods for preserving vacuum levels: a vacuum regulator and a
115 variable frequency drive (VFD).

116 An installation with a vacuum regulator requires that the vacuum pump run at full speed (usually
117 60 hertz). Almost all vacuum regulators installed today are servo or air-operated. Servo-operated
118 regulators are remote sensing, while air-operated regulators sense the vacuum inside the
119 regulator. Both units do an excellent job of vacuum regulation, provided they are correctly
120 installed and maintained. Proper installation requires that the regulator be placed on large enough
121 pipes and installed as close to the sanitary trap(s) as possible.

122 The vacuum regulator maintains a stable vacuum by allowing more or less air into the milking
123 system in response to vacuum changes. If there is a drop in vacuum in the system, the regulator
124 senses the drop and responds by closing down, allowing less air into the system. If there is an
125 increase in vacuum, the regulator will open more to allow more air to enter the system, thus
126 causing the vacuum to drop. These regulators are designed to have a response time of 50
127 milliseconds if they function correctly.

128 A VFD method for controlling the vacuum level is accomplished by running the vacuum pump
129 at different speeds depending on vacuum needs. The VFD is a tiny microprocessor that senses
130 vacuum change and sends a signal to the vacuum pump to adjust the speed of the motor. When
131 the vacuum is steady, the pump will run at a low frequency (i.e., 25 - 35 hertz). As the vacuum
132 level drops, the VFD sensor recognizes the vacuum drop and sends a signal to the VFD to
133 increase the pump frequency, thus producing more vacuum. As the vacuum need decreases, the
134 pump will slow down to prevent the vacuum level from overshooting. VFDs are utilized as a
135 method to save energy.

136 Receiver Group

137 The receiver group includes the receiver, sanitary trap, milk pump, and control panel. When milk
138 enters the milk line, it should travel simultaneously with air in a laminar pattern. The milk line
139 and receiver should be designed to flow slug-free along the bottom of the pipeline for at least
140 95% of the milking time.³ The milk line shall have a continuous slope of at least 0.8% (1 in./10

141 feet). Milk lines can be installed in either a high-line or low-line configuration. In the high line
142 configuration, the milk line is installed above the milking unit, and in a low line, the milk line is
143 installed below the milking unit (see Figure 2). In a highline system, vacuum creates a slug of
144 milk to raise the milk to the milk line from the milking unit. Therefore, milk is moved to the milk
145 line by moving alternating milk slugs followed by air slugs. In a low-line system, energy for milk
146 transport is provided by gravity. In low and high-line installations, once milk enters the pipeline,
147 it should travel simultaneously with air in a laminar pattern. In high-line systems, the system
148 vacuum must be adjusted for the vacuum needed to raise milk to the milk line. Most high-line
149 systems have vacuum levels set approximately 1-3" higher than low-line ones.

150 The receiver is where air and milk, which have been traveling together until now, separate. Milk
151 will travel to the milk storage area from this point via power supplied by the milk pump. A probe
152 in the receiver activates the milk pump when the milk level in the receiver reaches a specified
153 point. If milk passes through a plate cooler or chiller, the milk pump may have a variable speed
154 motor to keep a steady milk flow through the cooling device.

155 Milking Unit

156 The milking unit is made up of stainless steel or durable plastic. The milking unit is attached to
157 the milk line by a hose of a similar diameter as the claw outlet. Most of today's claws have a
158 minimum outlet of 5/8", with some as large as 7/8".

159 All claws need some form of claw vent, found either in the claw itself or the individual liners.
160 The vent helps assist the draining of the claw by reducing the hydrostatic head within the claw.
161 These vents are large enough to allow 0.25-0.5 cfm of free air into the claw.

162 The teacups are made up of a rigid outer shell in which milking liners are installed. Milking
163 liners are the only portion of the milk machine that comes in contact with the cow. There are
164 several hundred different liners on the market owing to the considerable disagreement amongst
165 dairymen regarding which are the best liners to milk cows properly. Liners are made of either
166 natural, synthetic, or silicone rubber. There are also differences in mouthpiece opening, length,
167 liner thickness, ability to re-tension, single or two-piece construction, and shape. Liner shapes
168 are round, triangle, or square. Liners collapse around the teat depending upon the liner shape.
169 Both round and square liners collapse against the teat at two points, even though the square liner
170 has four long sides. The triangle liner collapses in three points against the teat skin. During
171 milking, a continuous vacuum is present within the claw and liners to remove milk from the
172 claw. It is essential to realize that the teat end is constantly exposed to vacuum, even when the
173 liner is closed.

174 Pulsation Control

175 The pulsation system controls the actual process of milking the cow. The pulsator is an air valve
176 that alternates the flow of vacuum and atmospheric air into the pulsation chamber between the

177 liner shell and the liner. As vacuum is introduced into the pulsation chamber, the vacuum level
178 reaches a level higher than inside the liner barrel, causing the liner to open. This allows milk
179 flow to occur due to the difference in pressure in the teat compared to the airspace below the teat.
180 As atmospheric air is introduced into the pulsation chamber, the liner collapses around the teat
181 end to massage out the congestion (edema) that has collected during the milking process. Note
182 that the liner only collapses around the teat end (see Figures 3 and 4). Thus, liner closing only
183 mediates congestion within the teat end, not the entire teat.

184 Pulsators can be set to pulsate all four quarters simultaneously, called simultaneous pulsation or
185 alternating. With alternating pulsation, two liners are opened while the other two are closed, and
186 vice versa (see Figure 3). The alternating pattern can be either front to back or side to side. The
187 pulsation cycle is divided into four phases, representing one complete liner opening and closing.
188 The A Phase is when the vacuum is being moved through the pulsation lines into the chamber,
189 causing the liner to open. The B Phase is when the liner is completely open (see the left side of
190 Figure 4). The C Phase is when the vacuum is removed from the pulsation chamber and replaced
191 by air, causing the liner to close. The D Phase is the closed phase when the liner is in contact
192 with the teat end to massage the edema out of the teat end (see the right side of Figure 4).

193 The pulsator function is defined by its rate, ratio, and proportions of the cycle with each phase.
194 The pulsator rate is the number of complete cycles that occur per minute. The pulsator ratio is the
195 proportion of the cycle for which the liner is opening or open (A & B Phases) versus the
196 proportion for which it is closing or closed (C & D Phases). Pulsator rate and ratios vary from
197 farm to farm, but most farms use a rate of 45 – 65 beats per minute and ratios from 50:50 to
198 70:30 milk to rest ratio. The ASABE guidelines state that pulsators must provide at least 30% in
199 the B phase (milking phase) and not less than 15% and 150 milliseconds (ms) in the D phase
200 (massage phase).²

201 Figure 5 displays a pulsation graph from a vacuum recorder used to evaluate pulsator function
202 on-farm. The graph shows that the pulsator rate is approximately 60 beats per minute, and the
203 ratio is approximately 60:40. The B Phase has a minimum of 40% (390 ms). The D phase has a
204 minimum of 27% (272 ms) of the pulsator cycle.

205 The air supply to each pulsator may be drawn directly into the pulsator from the atmosphere or
206 through a filtered air system. The filtered air system prevents the pulsators from fouling due to
207 dirt accumulation within the working areas of the pulsator.

208 Automatic Cluster Removal

209 To increase labor efficiency and provide more consistent milking of cows from milking to
210 milking, many dairy farms have installed Automatic Cluster Removers (ACRs). ACRs utilize a
211 retractable arm or cord to remove the milking unit from the udder once the vacuum has ceased.
212 The end of milking is determined with either a milk meter that senses milk flow per minute or a

213 sensor that uses conductivity or optical density to determine when milk flow drops below a set
214 threshold.

215 Most ACRs come with a default setting from the factory of ~0.8 lbs./min. In addition, they also
216 have a delay setting, which is the time between when the sensors determine that the end of the
217 milking flow rate has been reached and when the milking unit is removed. Most milk quality
218 consultants feel ACRs should be adjusted with an end-of-milking endpoint set at 2 lbs./min or
219 higher and a delay time set as low as possible.

220 ACRs have a letdown delay usually set between 90-180 seconds. The letdown delay prevents the
221 ACR from prematurely removing the milking unit due to delayed milk letdown after the milking
222 unit is attached to the udder. On farms with good pre-milking stimulation, 90 seconds is usually
223 sufficient for milk letdown to occur. On farms milking cows 4-6 times per day in early lactation,
224 the letdown delay may need to be adjusted to prevent overmilking of these cows.

225 Conclusion

226 Development of milk equipment analysis to expand your practice can initially be daunting.
227 However, individuals need to realize that no matter how large or complex the milking system is,
228 the basic components of all systems are just multiples of the basic units. Applying NMC's
229 Procedures for Evaluating Vacuum Levels and Air Flow in Milking Systems systematically and
230 understanding the influences of your recommendations on milking unit performance and impacts
231 on the cow will lead to successful improvement in parlor performance. Additionally, it must be
232 remembered that milking equipment is only one contributor to overall milk quality on a dairy.
233 So, evaluating milking equipment without assessing milk harvest technician activity, the cows
234 and their environment, and overall farm management will often fail to lead to improvements in
235 milk quality.

236 References

- 237 1. ASAE EP445.1 Test Equipment and Its Application for Measuring Milking Machine
238 Operating Characteristics, July 1996, Published by American Society of Agricultural and
239 Biological Engineers, St Joseph, MO, Available at www.asabe.org.
- 240 2. ASAE S518.2 Milking Machine Installations – Construction and Performance, July 1996,
241 Published by American Society of Agricultural and Biological Engineers, St Joseph, MO,
242 Available at www.asabe.org.
- 243 3. Bramely, AJ, FH Dodd, GA Mein, and JA Bramley Editors, Machine Milking and
244 Lactation, Insight Books, 1992.
- 245 4. Delaval website, www.delaval.com.
- 246 5. Reinemann, DJ, PL Ruegg, N Schuring, Introduction to Milking Systems, UW-Madison
247 Short Course, 2000.
- 248 6. Reinemann, DJ, The History of Vacuum Regulation Technology, NMC Annual Meeting
249 Proceedings, 2005, 124-132.

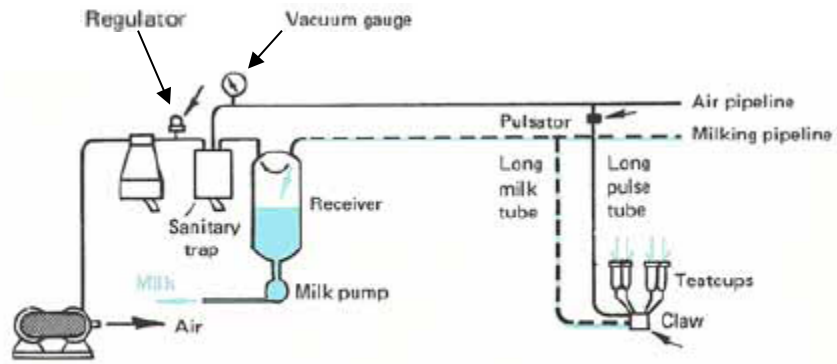
250

251

DRAFT

252 Figure 1 - Diagram of the basic milking system adopted from Reinemann⁶

253

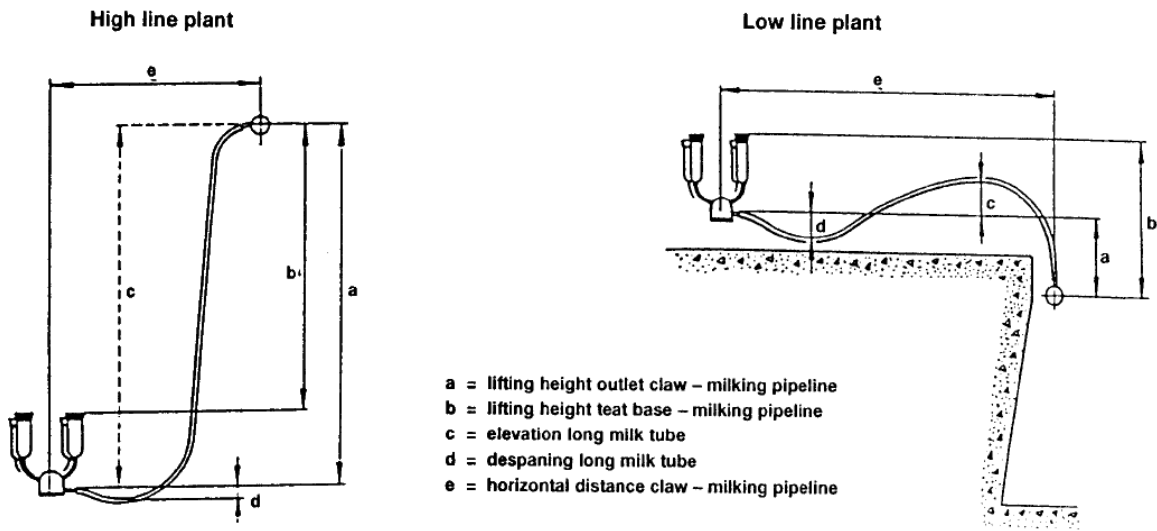


254

255

256

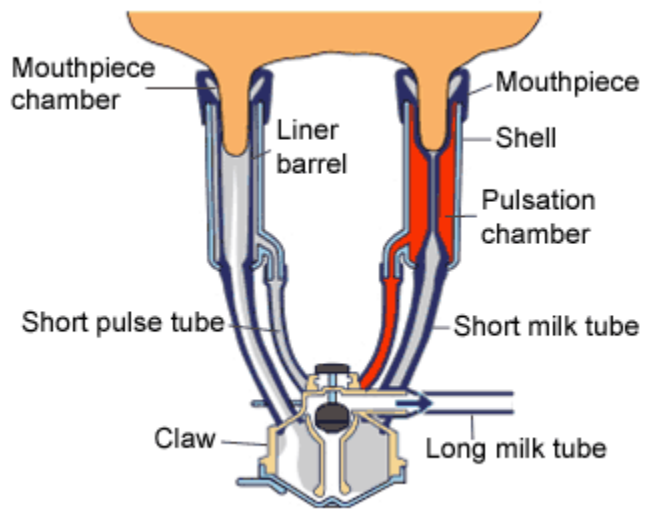
257 Figure 2 - Diagram of high and low line milk line installations.¹



258

259

260 Figure 3 - Adopted from the Delaval website.⁴

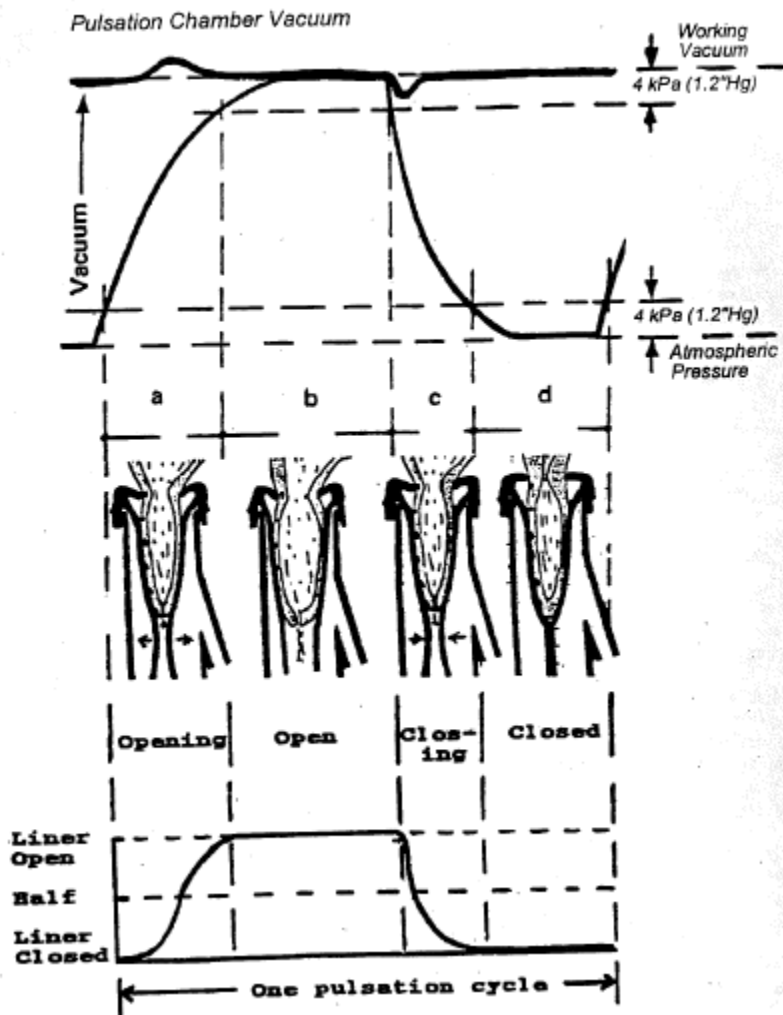


261

262

DRAFT

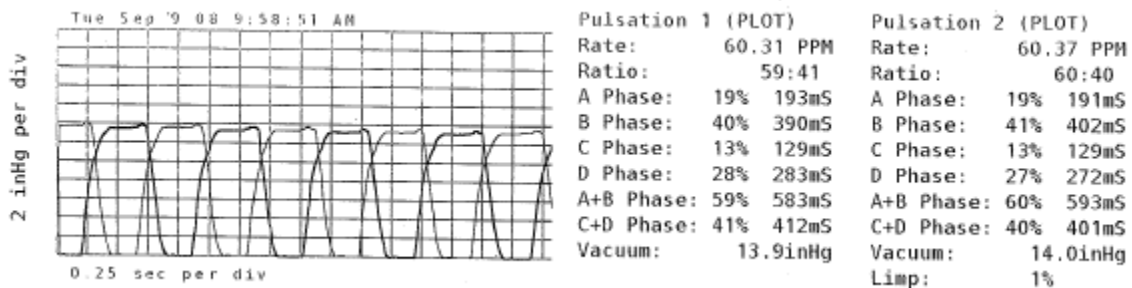
263 Figure 4 – Graph of a pulsation cycle depicting liner position and milk flow.⁵



264

265

266 Figure 5 – Pulsation graph from a vacuum recorder.



267

268